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**UTILITY PATENT APPLICATION TRANSMITTAL**

(Only for new non-provisional applications under 37 CFR 1.53(b))

Attorney Docket No. 42390.P7283Total Pages 2First Named Inventor or Application Identifier Simoni Ben-MichaelExpress Mail Label No. EL431886515US

ADDRESS TO: Assistant Commissioner for Patents  
 Box Patent Application  
 Washington, D. C. 20231

**APPLICATION ELEMENTS**

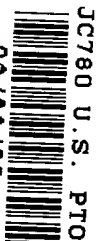
See MPEP chapter 600 concerning utility patent application contents.

1. X Fee Transmittal Form  
(Submit an original, and a duplicate for fee processing)
2. X Specification (Total Pages           )  
(preferred arrangement set forth below)
  - Descriptive Title of the Invention
  - Cross References to Related Applications
  - Statement Regarding Fed sponsored R & D
  - Reference to Microfiche Appendix
  - Background of the Invention
  - Brief Summary of the Invention
  - Brief Description of the Drawings (if filed)
  - Detailed Description
  - Claims
  - Abstract of the Disclosure
3. X Drawings(s) (35 USC 113) (Total Sheets 5)
4.        Oath or Declaration (Total Pages           )
  - a.        Newly Executed (Original or Copy)
  - b.        Copy from a Prior Application (37 CFR 1.63(d))  
(for Continuation/Divisional with Box 17 completed) (**Note Box 5 below**)
  - i.        DELETIONS OF INVENTOR(S) Signed statement attached deleting inventor(s) named in the prior application, see 37 CFR 1.63(d)(2) and 1.33(b).
5.        Incorporation By Reference (useable if Box 4b is checked)  
The entire disclosure of the prior application, from which a copy of the oath or declaration is supplied under Box 4b, is considered as being part of the disclosure of the accompanying application and is hereby incorporated by reference therein.
6.        Microfiche Computer Program (Appendix)

EL431886515US

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JC780 U.S. PTO

09/538015



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0633015-032000

7. ☐ Nucleotide and/or Amino Acid Sequence Submission  
(if applicable, all necessary)  
a. ☐ Computer Readable Copy  
b. ☐ Paper Copy (identical to computer copy)  
c. ☐ Statement verifying identity of above copies

**ACCOMPANYING APPLICATION PARTS**

8. ☐ Assignment Papers (cover sheet & documents(s))  
9. ☐ a. 37 CFR 3.73(b) Statement (where there is an assignee)  
☐ b. Power of Attorney  
10. ☐ English Translation Document (if applicable)  
11. ☐ a. Information Disclosure Statement (IDS)/PTO-1449  
☐ b. Copies of IDS Citations  
12. ☐ Preliminary Amendment  
13. ☒ Return Receipt Postcard (MPEP 503) (Should be specifically itemized)  
14. ☐ a. Small Entity Statement(s)  
☐ b. Statement filed in prior application, Status still proper and desired  
15. ☐ Certified Copy of Priority Document(s) (if foreign priority is claimed)  
16. Other: \_\_\_\_\_  
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17. **If a CONTINUING APPLICATION**, check appropriate box and supply the requisite information:

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Application for United States Letters Patent

for

**Resolving Link Frame Collisions for a Phone Line Network**

by

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## Field of Invention

The present invention is directed to network communications, and more specifically, to the transmission of link frames over a home phone line network.

## Background

5 The Home Phoneline Networking Alliance (HomePNA) is an incorporated, non-profit association of companies working to bring networking technology to the home. See [www.homepna.org](http://www.homepna.org). HomePNA envisions bringing Ethernet technology to the home by utilizing existing home phone wiring for the network physical medium. HomePNA provides specifications for the physical layer (PHY), its interface to an Ethernet MAC  
10 (Media Access Control), and its interface to the home phone wiring. See the IEEE (Institute of Electrical and Electronic Engineers) 802.3 standard for Ethernet.

The position of a HomePNA PHY in relationship to the OSI (Open Systems Interconnection) model is illustrated in Fig. 1. Logical Link Control (LLC) **102** and MAC **104** are implemented in accordance with IEEE 802.3, and HomePNA PHY **106**  
15 communicates with MAC **104** via interface **108**. Additional sublayers, and other optional layers, may be added to the layers shown in Fig. 1 so that PHY **106** may provide services to other communication protocols, such as Gigabit Ethernet. In practice, PHY **106** and MAC **104** may be integrated on a single die, so that interface **108** is not readily visible.

PHY **106** receives a MAC frame from MAC **104**, strips off the 8 octets of  
20 preamble and delimiter from the MAC frame, adds a HomePNA PHY header to form a HomePNA PHY frame, and transmits a PHY frame on physical medium **110**. Fig. 2 illustrates HomePNA PHY framing. A PHY frame comprises Ethernet Packet **202**, and appended to Ethernet Packet **202** is a HomePNA PHY header, comprising SYNC interval **204**, Access ID (Identification) **206**, Silence interval **208**, and PCOM field **210**.

25 A PHY frame is transmitted on physical medium **110** utilizing pulse position modulation (PPM). All PHY symbols transmitted on physical medium **110** comprise a pulse formed of an integer number of cycles of a square wave that has been filtered with a bandpass filter. The position of the pulse conveys the transmitted symbol. Differential signaling is employed, in which a pulse and its negative are transmitted on two wires for  
30 each transmitted symbol.

As indicated in Fig. 2, transmission begins with SYNC symbol 0, and Access ID field 206 is coded into seven AID (Access ID) symbols. SYNC symbol 0 may also be denoted as AID symbol 0. Access ID symbols 1 through 4 are used to identify individual stations to enable reliable collision detection. Access ID symbols 5 and 6 are used to transmit remote control management commands. AID symbol 7 is a silence interval.

SYNC symbol 0 and each AID symbol are 129 tics long, where 1 tic is defined as  $(7/60)10^{-6}$  seconds, which is approximately 116.667 nanoseconds. AID symbols 1 through 7 begin with a blanking interval of 60 tics, followed by a pulse positioned within one of four time slots to convey two bits of information. The time slots are separated by 20 tics, and are at positions 66, 86, 106, and 126 tics from the beginning of an AID symbol interval. SYNC symbol 0 is composed of a SYNC\_START pulse beginning at tic = 0 and a SYNC\_END pulse beginning at tic = 126.

In the example of Fig. 2, AID symbols 1 through 4 represent the Access ID word 00101101, where AID symbol 1 represents AID0 = 1 and AID1 = 0, AID symbol 2 represents AID2 = 1 and AID3 = 1, AID symbol 3 represents AID4 = 0 and AID5 = 1, and AID symbol 4 represents AID6 = 0 and AID7 = 0. AID symbols 5 and 6 represent the control word 0001, where AID symbol 5 represents Ctrl0 = 1 and Ctrl1 = 0, and AID symbol 7 represents Ctrl2 = 0 and Ctrl3 = 0.

A collision is detected only during AID symbols 0 through 7. If a transmitting station reads back an AID value that does not match its own, then a collision is indicated, and a JAM signal is transmitted to alert other stations. Non-transmitting stations may also detect non-conforming AID pulses as collisions. Only a transmitting station emits a JAM signal.

Fig. 3 illustrates in more detail MAC-to-HomePNA PHY interface 108. The signals RxD, RxClk, TxD, TxClk, TxEn, CRS, and COL are described in Table 1. HomePNA PHY 106 retains control of the TxClk and RxClk signals for clocking data synchronously in and out of MAC 104.

Table 1 HomePNA PHY-to-MAC Interface Signals.

MAC Interface Signal	Output From	Function
RxD	PHY	Data to the MAC is synchronously clocked by RX_CLK

MAC Interface Signal	Output From	Function
RxCik	PHY	Clock for RX DATA
TxD	MAC	Data to the PHY is synchronously clocked by TX_CLK
TxCik	PHY	Clock for TX DATA
TxEN	MAC	Transmit enable request from the MAC to begin sending data to the PHY.
CRS	PHY	Carrier Sense indicates the PHY is receiving a valid signal from the wiring network
COL	PHY	Collision. Indicates a collision was detected by the PHY on the wiring network

Devices connected to the network have the ability to detect whether they are connected to a “live” network or not by means of a valid link indication function.

- 5 HomePNA PHY 106 provides a valid link indication via signal Valid Link 302. Valid Link signal 302 may be provided to other layers or a management entity, and indicates whether link 110 is determined by PHY 106 to be functioning.

- 10 Each PHY on the network transmits a link frame if it has not transmitted a normal data frame or link frame for 2.0 seconds. The reception of a normal data PHY frame or a link frame causes a valid link indication. Non reception of data or link frames within a time period of not less than 4.0 seconds causes Valid Link signal 302 to indicate an invalid link indication.

- 15 Link frames are obtained from link packets by appending a HomePNA header as described in reference to Fig. 2. Link packets are defined by the HomePNA to be either runt packets, null-addressed packets, or self-addressed packets. Runt packets are less than 64 bytes in length. The HomePNA recommends that link packets be implemented as indicated in Table 2.

**Table 2. Link Packets**

**Option 1: Runt Packet** (14 bytes)

20

Field	Length	Description
Destination Address	6 bytes	The Destination address is either a NULL address (all zeros), or the originating station's MAC address.
Source Address	6 bytes	The Source address is either a NULL address (all zeroes), or the originating station's MAC address
Type/Length	2 bytes	The type/length field is set to a byte sequence value of 00-01 (hex). This value is an illegal length (not a type) that allows a promiscuous mode sniffer to determine that the runt is a HomePNA link frame.

**Option 2: Minimum Sized Packet** (64 bytes)

Field	Length	Description
Destination Address	6 bytes	The Destination address is either a NULL (all zeros), or the originating station's MAC address.
Source Address	6 bytes	The Source address is either a NULL address (all zeroes), or the originating station's MAC address
Type/Length	2 bytes	The Type/Length field is set to a byte sequence value of 00-2E (hex). This is a valid LLC length of 46 bytes.
LLC Test PDU Header	3 bytes	The DSAP field is set to a byte sequence value of 00-00-F3 (hex). This indicates a null-DSAP LLC test request frame.
Data	43 bytes	The data area of the link frame contains the following null terminated string:  "HomePNA (version 1.1) Link heartbeat frame"  This string allows promiscuous mode sniffers to determine that the frame is a HomePNA link frame.
CRC	4 bytes	Valid MAC CRC

Usually, the transmission of frames by a PHY requires a MAC layer. But for various market-demand reasons, it is desirable for a PHY to provide valid link indication functionality without assistance from a MAC or higher layer. This allows the use of Ethernet MAC chips that may not have valid link indication functionality built-in, and does not require the need to implement valid link indication functionality in software. The latter is important, not only because implementing valid link indication functionality in software may slow down system performance, but also because there may be power-saving states in which software will not work but for which link indication functionality is still needed. However, the requirement to have MAC functionality incorporated in a PHY is costly and leads to redundancy in devices that also have a MAC layer. It is therefore desirable for a PHY to have valid link indication functionality without the overhead of a MAC layer. There is also a need for a PHY to efficiently handle collisions between a link frame and a data frame, and between a link frame and another link frame. The present invention addresses these issues.

**Brief Description of the Drawings**

Fig. 1 illustrates the position of a HomePNA PHY within the OSI communication protocol stack.

Fig. 2 illustrates HomePNA PHY framing.

Fig. 3 illustrates a MAC-to-HomePNA PHY interface.

Fig. 4 provides a flow diagram for an embodiment of the present invention.

Fig. 5 provides a portion of the PHY architecture for an embodiment of the present invention.

### Description of Embodiments

Fig. 4 diagrams a method implemented by a HomePNA PHY according to an embodiment of the present invention. In Fig. 4, step 402 tests for whether a frame has been transmitted for the last 2.0 seconds. If no transmission has occurred in the last 2.0 seconds, then in step 404 the TxClk signal is stopped so that MAC 104 does not request PHY 106 to transmit a MAC frame, and a link frame is transmitted.

During transmission of the link frame in step 404, step 406 determines whether a collision is detected. If no collision is detected during transmission of the link frame, then the TxClk signal is enabled in step 407 so that MAC 104 is enabled to request transmission of MAC frames, and control is brought back to step 402. If a collision is detected, then a counter for keeping track of the number of collisions, referred to as Num\_Col, is set to zero in step 408, and control is brought to step 410.

In step 410 the link frame is re-transmitted after waiting an interval of time equal to IPG, the minimum Inter Packet Gap. Step 412 determines whether a collision is detected during re-transmission of the link frame. If there is no collision, then the TxClk signal is enabled in step 407 and control is brought back to step 402. If there is a collision, control is brought to step 414, whereupon the counter Num\_Col is incremented by one.

After Num\_Col is incremented by one in step 414, step 416 determines whether it is less than a positive integer  $N$ . If Num\_Col is less than  $N$ , control is brought back to step 410, whereupon the link frame is again re-transmitted after waiting an IPG. If, however, Num\_Col is no longer less than  $N$  in step 416, then control is brought to step 417 rather than looping back to step 410.

The loop defined by steps 410, 412, 414, and 416 causes a colliding link frame to be re-transmitted, with each re-transmission separated by an IPG, until either a collision-free link frame transmission has been accomplished, or until  $N$  re-transmissions have been made. Thus, counting the initial link frame transmission in step 404, when a link frame collides with another frame from another PHY, a sequence of back-to-back link



frames, each separated by an IPG, will be transmitted, up to a maximum number of  $N+1$  link frames. The integer  $N$  may be distinct for each HomePNA PHY, or may be the same for all HomePNA PHYs.

Once the number of re-transmissions for a colliding link frame has reached  $N$  (Num\_Col is no longer less than  $N$  in step 416), the TxClk signal is enabled in step 417 so that MAC 104 may request PHY 106 to transmit a MAC frame, and a random time interval is allowed to elapse in step 418 before control is brought back to step 402. The randomization provided in step 418 prevents a live-lock condition in which two colliding PHYs are each attempting to transmit a link frame.

Because step 410 re-transmits a colliding link frame after waiting only for an IPG, re-transmission of a colliding link frame is given higher priority than the re-transmission of a colliding data frame governed by the random process used for Ethernet, known as the truncated binary exponential backoff.

Fig. 5 provides a portion of the PHY architecture for an embodiment of the present invention. Finite state machine (FSM) 502 implements the flow diagram of Fig. 4. For simplicity, only the TxClk signal and Valid Link signal 302 are shown in Fig. 5. Counter 514 stores the value of Num\_Col as described in reference to Fig. 4. Collision detector 504 indicates to FSM 502 whether a collision is detected, and FSM 502 indicates to transceiver 512 when a link packet is to be transmitted according to the flow diagram of Fig. 4.

The random time interval generated in step 418 of Fig. 4 may be realized in Fig. 5 by ring oscillator 506, free-running counter 508, and latch 510. Ring oscillator 506 provides a clock signal to free-running counter 508, and is designed so that its frequency, and hence the clock signal used to clock counter 508, is a function of temperature, process, or other environmental factors. Counter 508 is sampled and latched by latch 510 to provide a random number. FSM 502 uses the random number stored in latch 510 to determine the random time interval in step 418.

FSM 502 may be realized by a programmable logic device, or an application specific integrated circuit. FMS 502 may also be realized by a programmable processor responsive to instructions stored as software or firmware. Various modifications may be made to the described embodiments without departing from the scope of the invention as

claimed below. For example, another embodiment may follow the flow diagram in Fig. 4, with the exception that if step 416 is answered in the negative, step 417 is not implemented, and after step 418, Num\_Col is re-set to zero and control is brought immediately to step 410 rather than to step 402. In another embodiment, a time interval  
5 other than IPG may be used in step 410. For example, a positive random variable may be added to IPG before re-transmitting a link frame in step 410, so that a collision among colliding link frames may be more quickly resolved. However, such an approach may not give maximum priority to link frame re-transmission.

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What is claimed is:

1. A method for a PHY to resolve link frame collisions, the method comprising:
  - (i) attempting to transmit a link frame if the PHY has not transmitted a frame in the last  $x$  seconds, where  $x$  is a positive real number; and
  - (ii) if a frame collision is detected during step (i), attempting to transmit a link frame at a time interval after the last frame transmission attempt of the PHY has ended.
2. The method as set forth in claim 1, further comprising:
  - (iii) repeating claim limitation (ii) each time a frame collision is detected until the number of link frame transmission attempts since the occurrence of claim limitation (i) equals a specified limit.
3. The method as set forth in claim 2, further comprising:
  - (iv) if in performing claim limitation (iii) the number of link frame transmission attempts since the occurrence of claim limitation (i) equals the specified limit, performing claim limitations (i) and (ii) upon allowing a random interval of time to elapse after the last link frame transmission attempt of the PHY has ended.
4. The method as set forth in claim 1, wherein the time interval is an Inter Packet Gap (IPG).
5. The method as set forth in claim 4, further comprising:

(iii) repeating claim limitation (ii) each time a frame collision is detected until the number of link frame transmission attempts since the occurrence of claim limitation (i) equals a specified limit.

6. The method as set forth in claim 5, further comprising:

(iv) if in performing claim limitation (iii) the number of link frame transmission attempts since the occurrence of claim limitation (i) equals the specified limit, performing claim limitations (i) and (ii) upon allowing a random interval of time to elapse after the last link frame transmission attempt of the PHY has ended.

7. A PHY comprising:

a transceiver to transmit and receive frames on a network; and

a finite state machine; wherein

while the finite state machine is in a first state, the PHY monitors frame transmissions by the transceiver; and

while the finite state machine is in a second state, the PHY attempts link frame transmissions such that each link frame transmission is attempted at a time interval after the last frame transmission attempt has ended.

8. The PHY as set forth in claim 7, wherein

while the finite state machine is in a third state, the PHY does not transmit any link frames, wherein the finite state machine transitions from the third state to the first state after a random time interval upon entering the third state;

the finite state machine transitions from the first state to the second state if there has been no frame transmission for a time period;

the finite state machine causes the transceiver to attempt to transmit a link frame when transitioning from the first state to the second state; and

the finite state machine transitions from the second state to the first state if no frame collision is detected since the last frame transmission attempt.

9. The PHY as set forth in claim 8, wherein

the finite state machine transitions from the second state to the third state if the number of link frame transmissions since entering the second state is equal to a specified limit.

10. The PHY as set forth in claim 9, wherein

while the finite state machine is in the first state and the third state, a PHY-to-MAC transmit-clock signal is enabled; and

while the finite state machine is in the second state, the PHY-to-MAC transmit-clock signal is disabled.

11. The PHY as set forth in claim 7, wherein the time interval is an Inter Packet Gap (IPG).

12. The PHY as set forth in claim 11, wherein

while the finite state machine is in a third state, the PHY does not transmit any link frames, wherein the finite state machine transitions from the third state to the first state after a random time interval upon entering the third state;

the finite state machine transitions from the first state to the second state if there has been no frame transmission for a time period;

the finite state machine causes the transceiver to attempt to transmit a link frame when transitioning from the first state to the second state; and

the finite state machine transitions from the second state to the first state if no frame collision is detected since the last frame transmission attempt.

13. The PHY as set forth in claim 12, wherein

the finite state machine transitions from the second state to the third state if the number of link frame transmissions since entering the second state is equal to a specified limit.

14. The PHY as set forth in claim 13, wherein

while the finite state machine is in the first state and the third state, a PHY-to-MAC transmit-clock signal is enabled; and

while the finite state machine is in the second state, the PHY-to-MAC transmit-clock signal is disabled.

15. A PHY comprising:

a transceiver to attempt to transmit a first link frame if the PHY has not transmitted a frame for a time period; and

a collision detector, wherein if a first collision is detected by the collision detector during the attempt to transmit the first link frame, the PHY attempts to transmit a second link frame a time interval equal to an Inter Packet Gap (IPG) after transmission of the first link frame.

16. The PHY as set forth in claim 15, further comprising:

a counter, wherein the counter is changed by an increment if the collision detector detects a second collision when the PHY attempts to transmit the second link frame.

17. The PHY as set forth in claim 16, further comprising:

a free-running counter; and

an oscillator to clock the free-running counter, wherein the free-running counter provides a random number so that if the counter is equal to a specified limit when another frame collision is detected, a random time interval is allowed to elapse before another link frame is attempted to be transmitted.

18. A communication system comprising:

a network comprising a home phone line; and

a PHY coupled to the network to transmit and receive frames, the PHY comprising:

a transceiver to attempt to transmit a first link frame if the PHY has not transmitted a frame for a time period; and

a collision detector, wherein if a first collision is detected by the collision detector during the attempt to transmit the first link frame, the PHY attempts to transmit a second link frame a time interval equal to an Inter Packet Gap (IPG) after transmission of the first link frame.

19. The communication system as set forth in claim 18, wherein the PHY further comprises:

a counter, wherein the counter is changed by an increment if the collision detector detects a second collision when the PHY attempts to transmit the second link frame.

20. The communication system as set forth in claim 19, wherein the PHY further comprises:

a free-running counter; and

an oscillator to clock the free-running counter, wherein the free-running counter provides a random number so that if the counter is equal to a specified limit when another frame collision is detected, a random time interval is allowed to elapse before another link frame is attempted to be transmitted.



### Abstract

A PHY for transmitting link frames on a home phone line network without the need of a MAC layer. The PHY transmits an initial link frame if the PHY has not transmitted a frame for a time interval, as specified by the Home Phoneline Networking Alliance. After transmission of the initial link frame, the transmit-clock signal to the MAC is disabled so that the MAC does not request the PHY to transmit a frame. If a collision is detected during transmission of the initial link frame, a counter is set to zero and the PHY transmits back-to-back link frames, where the initial link frame and the back-to-back link frames are each separated by an IPG (Inter Packet Gap). When transmitting these back-to-back link frames, the counter is incremented each time a collision is detected. When the counter equals a specified number, the transmit-clock signal to the MAC is enabled and the PHY waits for a random interval of time before beginning the above-described process again. This process is repeated until a link frame is successfully transmitted without a collision. In this way, higher priority is given to colliding link frames than to colliding data frames, and the case of colliding link frames is efficiently handled by the randomization process so that a live-lock situation is prevented.

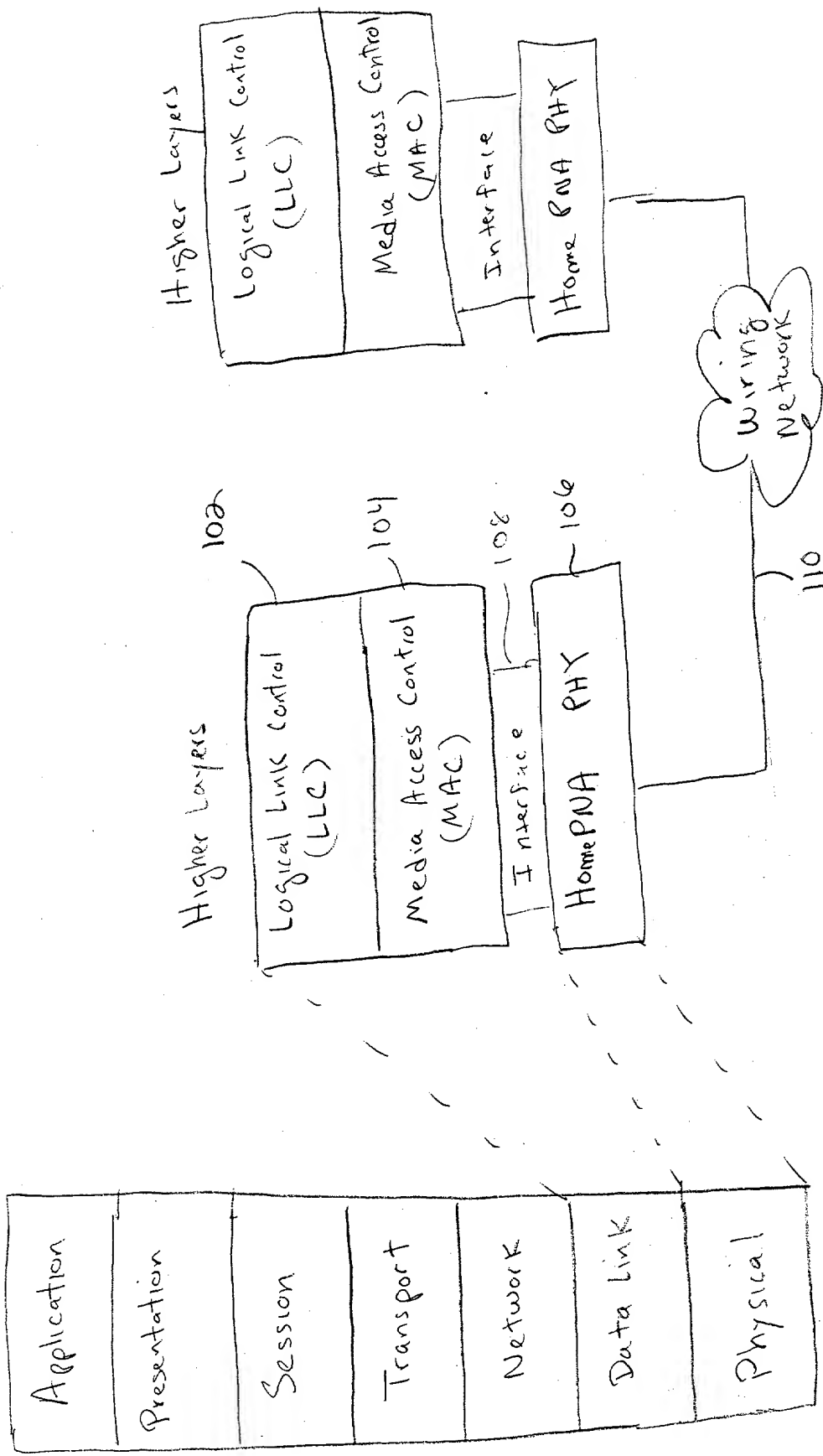


Fig-1 (Prior Art)

[illegible]

1 Tic = 116.6667 nsec  
 \_\_\_\_\_ = receiver blanking interval

DECEMBER 2006

MAC to Home PNA PHY Interface

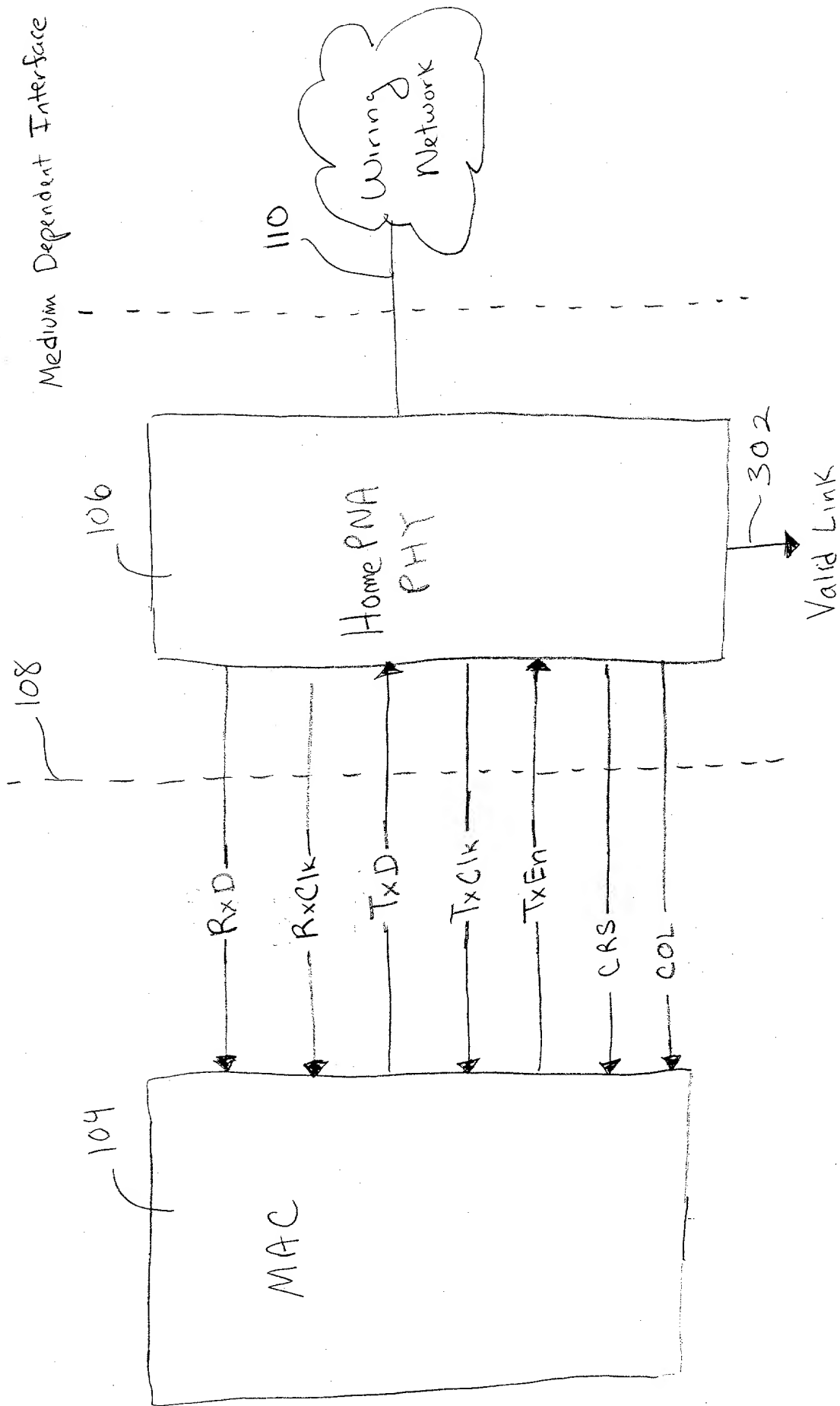


Fig. 3 (Prior Art)

1990-1991		1991-1992		1992-1993		1993-1994		1994-1995		1995-1996		1996-1997		1997-1998		1998-1999		1999-2000		2000-2001		2001-2002		2002-2003		2003-2004		2004-2005		2005-2006		2006-2007		2007-2008		2008-2009		2009-2010		2010-2011		2011-2012		2012-2013		2013-2014		2014-2015		2015-2016		2016-2017		2017-2018		2018-2019		2019-2020		2020-2021		2021-2022		2022-2023		2023-2024		2024-2025		2025-2026		2026-2027		2027-2028		2028-2029		2029-2030		2030-2031		2031-2032		2032-2033		2033-2034		2034-2035		2035-2036		2036-2037		2037-2038		2038-2039		2039-2040		2040-2041		2041-2042		2042-2043		2043-2044		2044-2045		2045-2046		2046-2047		2047-2048		2048-2049		2049-2050		2050-2051		2051-2052		2052-2053		2053-2054		2054-2055		2055-2056		2056-2057		2057-2058		2058-2059		2059-2060		2060-2061		2061-2062		2062-2063		2063-2064		2064-2065		2065-2066		2066-2067		2067-2068		2068-2069		2069-2070		2070-2071		2071-2072		2072-2073		2073-2074		2074-2075		2075-2076		2076-2077		2077-2078		2078-2079		2079-2080		2080-2081		2081-2082		2082-2083		2083-2084		2084-2085		2085-2086		2086-2087		2087-2088		2088-2089		2089-2090		2090-2091		2091-2092		2092-2093		2093-2094		2094-2095		2095-2096		2096-2097		2097-2098		2098-2099		2099-2100		2100-2101		2101-2102		2102-2103		2103-2104		2104-2105		2105-2106		2106-2107		2107-2108		2108-2109		2109-2110		2110-2111		2111-2112		2112-2113		2113-2114		2114-2115		2115-2116		2116-2117		2117-2118		2118-2119		2119-2120		2120-2121		2121-2122		2122-2123		2123-2124		2124-2125		2125-2126		2126-2127		2127-2128		2128-2129		2129-2130		2130-2131		2131-2132		2132-2133		2133-2134		2134-2135		2135-2136		2136-2137		2137-2138		2138-2139		2139-2140		2140-2141		2141-2142		2142-2143		2143-2144		2144-2145		2145-2146		2146-2147		2147-2148		2148-2149		2149-2150		2150-2151		2151-2152		2152-2153		2153-2154		2154-2155		2155-2156		2156-2157		2157-2158		2158-2159		2159-2160		2160-2161		2161-2162		2162-2163		2163-2164		2164-2165		2165-2166		2166-2167		2167-2168		2168-2169		2169-2170		2170-2171		2171-2172		2172-2173		2173-2174		2174-2175		2175-2176		2176-2177		2177-2178		2178-2179		2179-2180		2180-2181		2181-2182		2182-2183		2183-2184		2184-2185		2185-2186		2186-2187		2187-2188		2188-2189		2189-2190		2190-2191		2191-2192		2192-2193		2193-2194		2194-2195		2195-2196		2196-2197		2197-2198		2198-2199		2199-2200		2200-2201		2201-2202		2202-2203		2203-2204		2204-2205		2205-2206		2206-2207		2207-2208		2208-2209		2209-2210		2210-2211		2211-2212		2212-2213		2213-2214		2214-2215		2215-2216		2216-2217	
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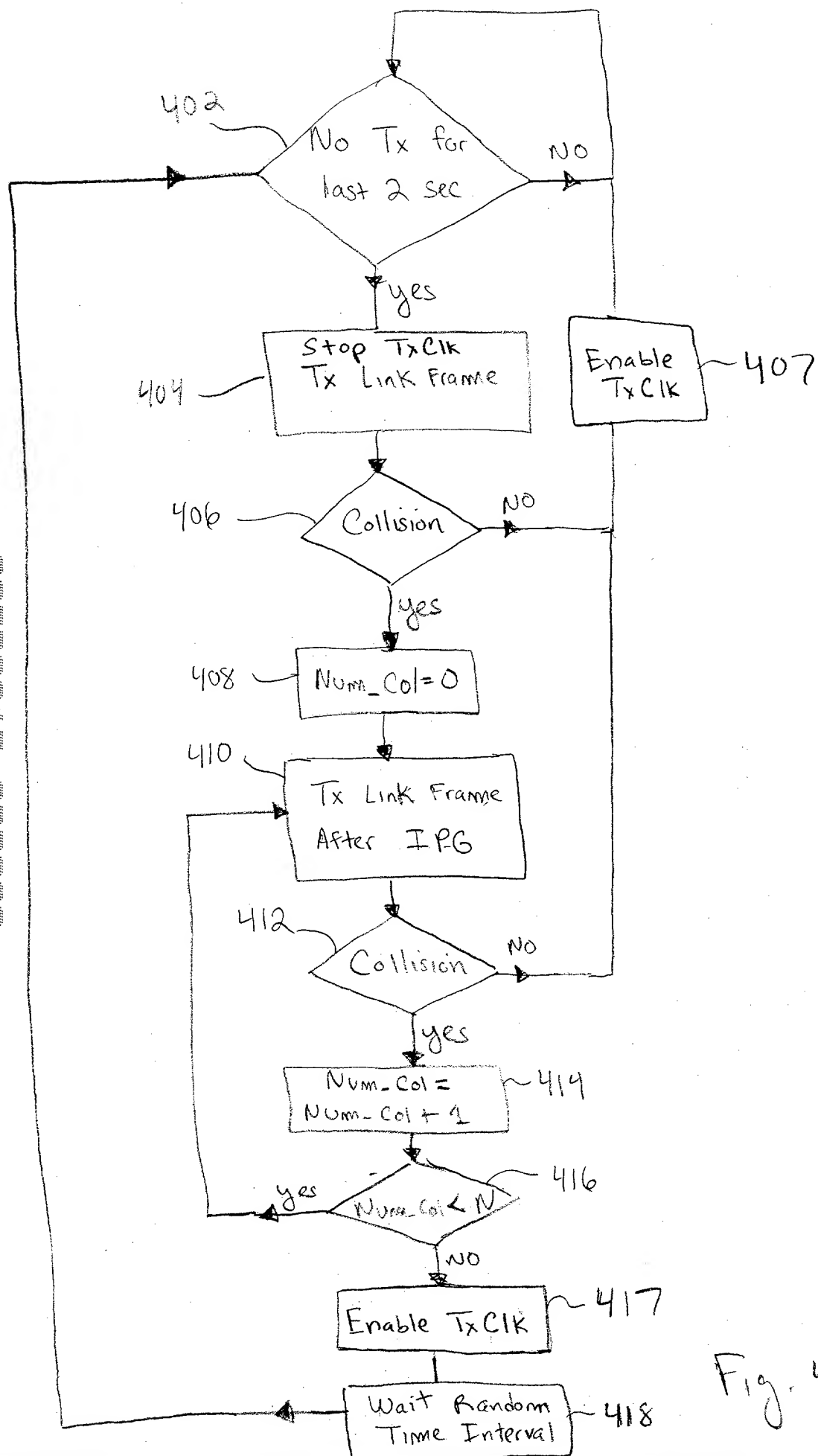


Fig. 4

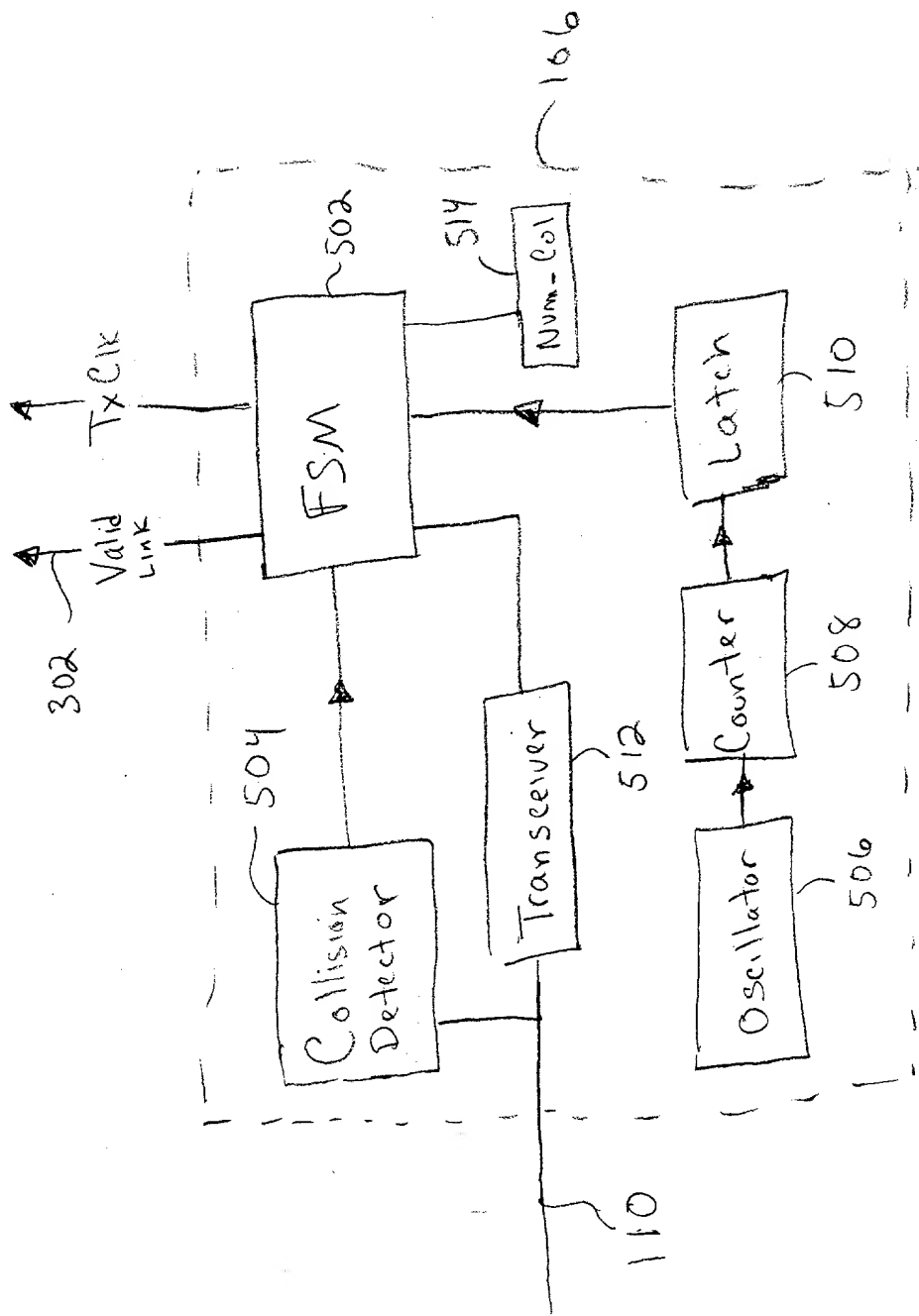


Fig. 5